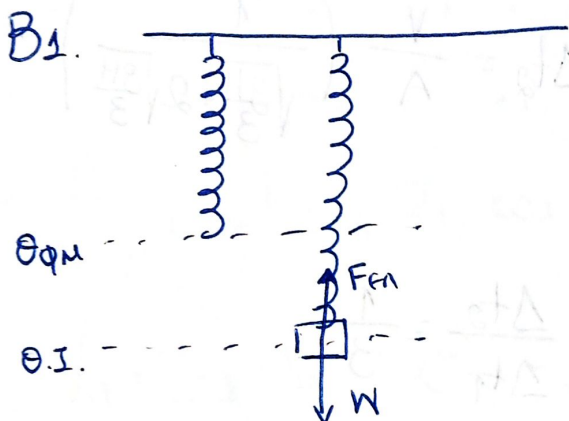


ΦΥΣΙΚΗ

ΘΕΜΑ Α

A1. γ A2. δ A3. γ A4. β A5. α.1 β.2 γ.1 δ.2 ε.2

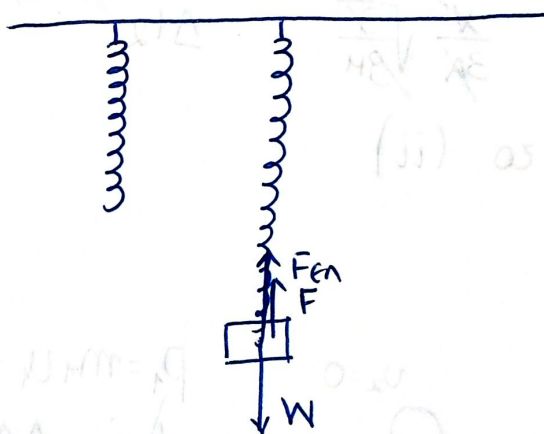
ΘΕΜΑ Β



Θ.Ι.: $\sum F = 0 \Rightarrow F_{ελ} = W \Rightarrow k \Delta l_1 = mg \Rightarrow \Delta l_1 = \frac{mg}{k}$

Πείραμα 1° : $A_1 = \Delta l_1 = \frac{mg}{k}$ ①

Πείραμα 2° :



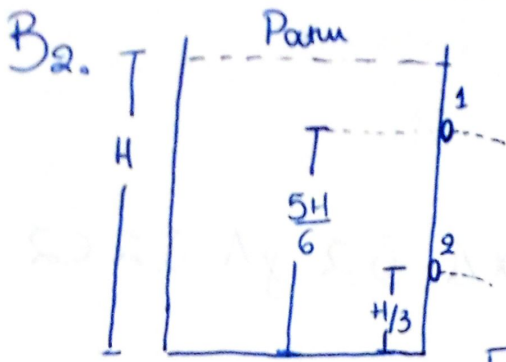
Ν.Θ.Ι.: $\sum F = 0 \Rightarrow F_{ελ} + F = W \Rightarrow k \Delta l_2 + mg = mg \Rightarrow k \Delta l_2 = 0 \Rightarrow \Delta l_2 = 0$

Άρα η νέα α.α.τ. γίνεται γύρω από τη Θ.Φ.Μ. (Ν.Θ.Ι.) και έχει ακραία θέση τη Θ.Ι. πριν ασκηθεί η δύναμη F.

Άρα $A_2 = \Delta l_1 = \frac{mg}{k}$ ②

Από ①, ② έχουμε ότι $A_1 = A_2$

Σωστή απάντηση το (i)



Orin (1)

Bernoulli: $P_{atm} + \frac{1}{2} \rho v_{atm}^2 + \rho g H = P_{atm} + \frac{1}{2} \rho v_1^2 + \rho g \frac{5H}{6}$

$$v_1^2 = g \frac{2H}{6} \Rightarrow v_1 = \sqrt{\frac{gH}{3}}$$

$$\Pi_1 = A \cdot v_1 \Rightarrow \frac{V}{\Delta t_1} = A \cdot v_1 \Rightarrow \Delta t_1 = \frac{V}{A \sqrt{\frac{gH}{3}}} = \frac{V}{A} \sqrt{\frac{3}{gH}} \quad (1)$$

Orin (1)+(2)

Orin Toricelli: $v_2 = \sqrt{2g \frac{2H}{3}} = \sqrt{\frac{4gH}{3}}$

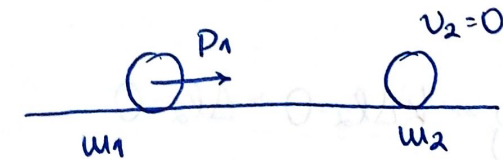
$$\Pi = A \cdot v_1 + A \cdot v_2 \Rightarrow \frac{V}{\Delta t_2} = A \left(\sqrt{\frac{gH}{3}} + \sqrt{\frac{4gH}{3}} \right) \Rightarrow \Delta t_2 = \frac{V}{A} \left(\frac{1}{\sqrt{\frac{gH}{3}} + 2\sqrt{\frac{gH}{3}}} \right) \Rightarrow$$

$$\Delta t_2 = \frac{V}{A} \left(\frac{1}{3\sqrt{\frac{gH}{3}}} \right) = \frac{V}{A \cdot 3} \sqrt{\frac{3}{gH}} \quad (2)$$

Orin $\frac{(1)}{(2)} \Rightarrow \frac{\Delta t_1}{\Delta t_2} = \frac{\frac{V}{A} \sqrt{\frac{3}{gH}}}{\frac{V}{3A} \sqrt{\frac{3}{gH}}} \Rightarrow \frac{\Delta t_1}{\Delta t_2} = 3 \Rightarrow \frac{\Delta t_2}{\Delta t_1} = \frac{1}{3}$

Zwei antworten zu (ii)

B₃.



$p_1 = m_1 v_1 \Rightarrow v_1^2 = \frac{p_1^2}{m_1^2}$ ohoia $v_1'^2 = \frac{p_1'^2}{m_1^2}$

Orin ΔO

$P_{APX} = P_{TEA} \Rightarrow p_1 + p_2' = p_1' + p_2' \Rightarrow$

$p_1 = \frac{p_1}{5} + p_2' \Rightarrow p_2' = \frac{4p_1}{5}$

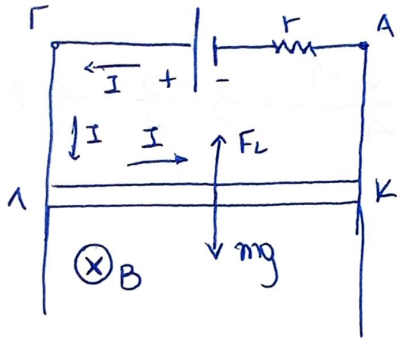
$$\Pi \% = \frac{|\Delta K|}{K_{APX}} \cdot 100\% = \frac{K_{TEA} - K_{TEA}}{K_{APX}} \cdot 100\% = \left(1 - \frac{K_{TEA}}{K_{APX}} \right) \cdot 100\% =$$

$$= \left(1 - \frac{\frac{1}{2} m_1 v_1'^2}{\frac{1}{2} m_1 v_1^2} \right) \cdot 100\% = \left(1 - \frac{\frac{1}{2} \frac{p_1'^2}{m_1}}{\frac{1}{2} \frac{p_1^2}{m_1}} \right) \cdot 100\% = \left(1 - \frac{p_1'^2}{p_1^2} \right) \cdot 100\% =$$

$$= \left(1 - \frac{1}{25} \right) \cdot 100\% = \frac{24}{25} \cdot 100\% = 24 \cdot 4\% = 96\%$$

Zwei antworten zu (iii)

ΘΕΜΑ Γ



Γ1. Αικίνηται από ισορροπεί:

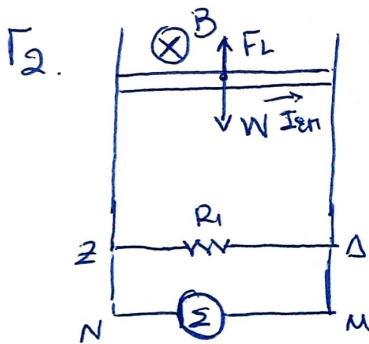
$$\sum F = 0 \Rightarrow F_L = W \Rightarrow BIl = mg \Rightarrow B = \frac{mg}{Il} \Rightarrow$$

$$B = \frac{mg}{\frac{\epsilon}{R_{on}} l} = \frac{R_{on} mg}{\epsilon \cdot l} = \frac{(R_{κλ} + r) mg}{\epsilon l} \Rightarrow$$

$$B = \frac{(2+1) \cdot 0,3 \cdot 10}{9 \cdot 1} = \frac{3 \cdot 3}{9} = 1 \text{ T}$$

$$I = \frac{\epsilon}{R_{on}} = \frac{9}{3} = 3 \text{ A}$$

Από κανόνα δεξιάς χείριού αφού η F_L είναι προς τα επάνω για να ισορροπεί το B είναι από τον αναγκαστικό προς τη σελίδα.



Γ2. Αφού ανοίγω το Σ πρέπει να υπάρχει ϵ , άρα και I . Άρα ο κλ ορμίζει να κατέρχεται εξαιτίας του W . Εμφανίζεται I_{en} και F_L ώστε να αντισταθεί συν Σ mm. Επομένως αφού $\sum F = ma \Rightarrow$

$$W - F_L = ma \Rightarrow$$

$$W - \frac{B^2 u \cdot l^2}{R_{on}} = ma$$

$$F_L = B \cdot I_{en} \cdot l \quad (1)$$

$$I_{en} = \frac{\epsilon_{en}}{R_{on}} \quad (2)$$

$$\epsilon_{en} = \left| \frac{d\Phi}{dt} \right| N = \frac{d(BA)}{dt} N = B \cdot u \cdot l \quad (3)$$

$$(1) \xrightarrow{(2)} \xrightarrow{(3)} F_L = \frac{B^2 u l^2}{R_{on}} \quad (4)$$

ο αγωγός κατέρχεται επιταχυνόμενα με προϋκμένη επιτάχυνση

μέχρι να ανακτίσει u_{op} . Από εκείνη τη στιγμή και έπειτα εκτελεί Ε.Ο.Κ.

$$u_{op} \text{ όταν } a=0 \Rightarrow \sum F = 0 \Rightarrow F_L = mg \Rightarrow \frac{B^2 u_{op} l^2}{R_{on}} = mg \Rightarrow u_{op} = \frac{mg R_{on}}{B^2 \cdot l^2} \quad (5)$$

$$\text{Για συνθετική } P_{\Sigma} = \frac{V_{\Sigma}^2}{R_{\Sigma}} \Rightarrow R_{\Sigma} = \frac{V_{\Sigma}^2}{P_{\Sigma}} = \frac{6^2}{6} = 6 \Omega$$

$$R_{\Sigma} = \frac{R_1 \cdot R_2}{R_1 + R_2} = \frac{3 \cdot 6}{3+6} = 2 \Omega \quad R_{on} = R_{1,\Sigma} + R_{κλ} = 2+2 = 4 \Omega$$

$$\textcircled{5} \Rightarrow u_{op} = \frac{0.3 \cdot 10 \cdot 4}{1^2 \cdot 1^2} = 12 \text{ m/s}$$

$$\Gamma_3. \frac{dp}{dt} = \Sigma F = W - F_L = mg - \frac{B^2 u_{op} / 2 \ell^2}{R_{on}} = 0.3 \cdot 10 - \frac{1 \cdot 6 \cdot 1}{4} = 3 - \frac{3}{2} = \frac{3}{2} \text{ N}$$

$\Gamma_4.$ Όταν $u = u_{op}$ τότε :

$$I_{en} = \frac{B u \ell}{R_{on}} = \frac{1 \cdot u_{op} \cdot 1}{4} = \frac{12}{4} = 3 \text{ A}$$

Η τάση στο R_1 και στη συσκευή είναι η παθητική ζώνη αέρα

$$V_{\pi} = V_{\Sigma \Delta} = V_{NM} = \mathcal{E}_{en} - I_{en} \cdot R_{en} \quad \textcircled{6}$$

$$\mathcal{E}_{en} = B u_{op} \ell = 1 \cdot 12 \cdot 1 = 12 \text{ V}$$

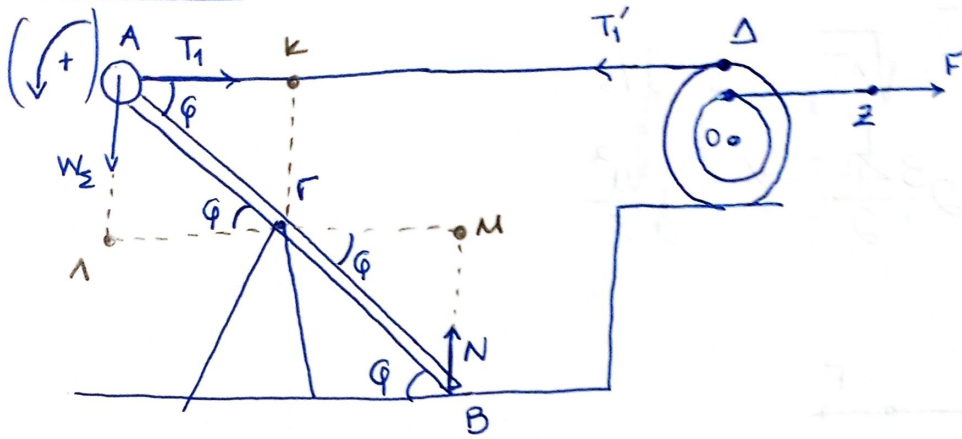
$$\textcircled{6} \Rightarrow V_{NM} = 12 - 3 \cdot 2 = 6 \text{ V}$$

$$\text{Άρα } P = \frac{V_{NM}^2}{R_{\Sigma}} = \frac{6^2}{6} = 6 \text{ W}$$

Άρα η συσκευή λειτουργεί κανονικά.



ΘΕΜΑ Δ



$$\Delta_1. \sum \tau_r = 0 \Rightarrow T_1 \cdot K\Gamma - W_2 \Gamma\Lambda = N \cdot \Gamma M \Rightarrow$$

$$T_1 \cdot \eta \mu \varphi \cdot \frac{l}{2} - W_2 \sigma \upsilon \nu \varphi \cdot \frac{l}{2} = N \cdot \sigma \upsilon \nu \varphi \cdot \frac{l}{2} \Rightarrow$$

$$10,5 \cdot 0,8 - m_2 g \cdot 0,6 = N \cdot 0,6 \Rightarrow$$

$$\frac{10,5 \cdot 8}{10^3} - 10 \cdot 6 = N \cdot 6 \Rightarrow$$

$$N = \frac{42}{3} - 10 = 14 - 10 \Rightarrow N = 4 \text{ N}$$

$$\Delta_2. \frac{\Delta L}{\Delta t} = \sum \tau_r = I_p \cdot \alpha_y = \frac{1}{12} M L^2 \alpha_y = \frac{1}{12} \cdot 3 \cdot 4 \cdot 3 = 3 \text{ N} \cdot \text{m}$$

$$\underline{\text{ΣΥΣΤΗΜΑ}}: \sum \tau_r = I_2 \cdot \alpha_y \Rightarrow W_2 \cdot \frac{l}{2} \sigma \upsilon \nu \varphi = I_2 \cdot \alpha_y \omega \nu \Rightarrow$$

$$\alpha_y \omega \nu = \frac{1 \cdot 10 \cdot \frac{3}{2} \cdot 0,6}{2} = 3 \text{ rad/s}^2$$

$$\Delta_3. |\Delta L| = |L_{\text{ΤΕΛ}} - L_{\text{ΑΡΧ}}| = |I_2 \cdot \frac{\omega}{2} - I_2 \cdot \omega| = I_2 \frac{3\omega}{2} \quad (2)$$

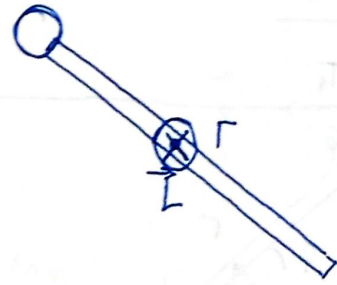
$$I_2 = I_p + m \left(\frac{l}{2} \right)^2 = \frac{1}{12} M L^2 + m \frac{l^2}{4} = \frac{1}{12} 3 \cdot 4 + 1 \cdot \frac{4}{4} = 1 + 1 = 2 \text{ kgm}^2$$

$$\underline{\text{ΘΜΚΕ}}: K_{\text{ΤΕΛ}} - K_{\text{ΑΡΧ}} = \sum W \Rightarrow \frac{1}{2} I_2 \omega^2 = m g \cdot h \Rightarrow \omega = \sqrt{\frac{2 m g h}{I_2}} \quad (1)$$

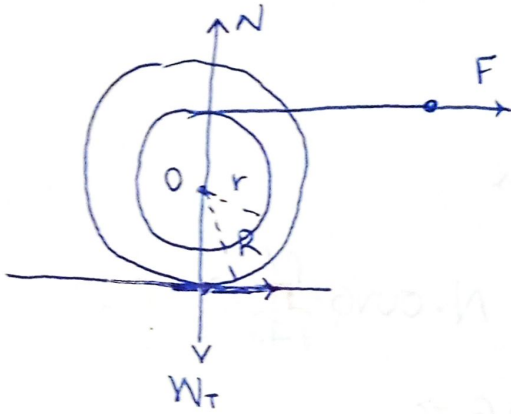
$$h = \pi r \phi \cdot \omega = 0,8 \cdot 2 = 1,6 \text{ m.}$$

$$(1) \Rightarrow \omega = \sqrt{\frac{2 \cdot 1 \cdot 10 \cdot 1,6}{2}} = \sqrt{16} = 4 \text{ rad/s}$$

$$(2) \Rightarrow |\Delta L| = I_2 \cdot \frac{3\omega}{2} = 2 \cdot \frac{3 \cdot 4}{2} = 12 \text{ kg} \frac{\text{m}^2}{\text{s}}$$



4.



$$\sum \tau_O = I_T \cdot \alpha_{\text{cm}} \Rightarrow F \cdot r - T_{\text{fr}} \cdot R = \frac{1}{2} M_T R^2 \alpha_{\text{cm}} \Rightarrow F r - T_{\text{fr}} R = \frac{1}{2} M_T R \alpha_{\text{cm}} \quad (3)$$

$$\sum F_x = M_T \alpha_{\text{cm}} \Rightarrow F + T_{\text{fr}} = M_T \alpha_{\text{cm}} \Rightarrow -T_{\text{fr}} = F - M_T \alpha_{\text{cm}} \quad (4)$$

$$(3) \stackrel{(4)}{\Rightarrow} F \cdot r + (F - M_T \alpha_{\text{cm}}) R = \frac{1}{2} M_T R \alpha_{\text{cm}} \Rightarrow$$

$$F r + F R - M_T \alpha_{\text{cm}} R = \frac{1}{2} M_T R \alpha_{\text{cm}} \Rightarrow$$

$$F(R+r) = \frac{3}{2} M_T R \alpha_{\text{cm}} \Rightarrow \alpha_{\text{cm}} = \frac{2F(R+r)}{3M_T R} = \frac{2 \cdot 12(0,4+0,3)}{3 \cdot 7 \cdot 0,4}$$

$$= \frac{2 \cdot 12 \cdot 0,7}{3 \cdot 7 \cdot 0,4} = 2 \text{ m/s}^2$$

$$\Delta 5. 0 \rightarrow 2 \text{ s} : \Delta x = \frac{1}{2} \alpha_{\text{cm}} t^2 = \frac{1}{2} 2 \cdot 2^2 = 4 \text{ m.}$$

$$\Delta \theta = \frac{1}{2} \alpha_{\text{rot}} t^2 = \frac{1}{2} \frac{\alpha_{\text{cm}}}{R} t^2 = \frac{1}{2} \frac{2}{0,4} \cdot 4 = 10 \text{ rad}$$

$$W_F = W_{F_{\text{мет}}} + W_{F_{\text{тр}}} = F \cdot \Delta x + F \cdot r \Delta \theta = 12 \cdot 4 + 12 \cdot 0,3 \cdot 10 = 12 \cdot 7 = 84 \text{ J.}$$